



Advances in Self-Consistent Accelerator modeling

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Advances in Self-Consistent Electromagnetic Modeling

- Complex cavity computations with particles have been improved through algorithms, including parallelization, making possible computations of wakefields in complex structures, intrabunch effects, injectors, ...
- Summary of some of what has made this possible
 - Local charge and current deposition methods
 - Parallelization
 - Improved stability
 - Boundary representations
- Comparison with
 - Finite element approaches
 - Unitary separation approaches

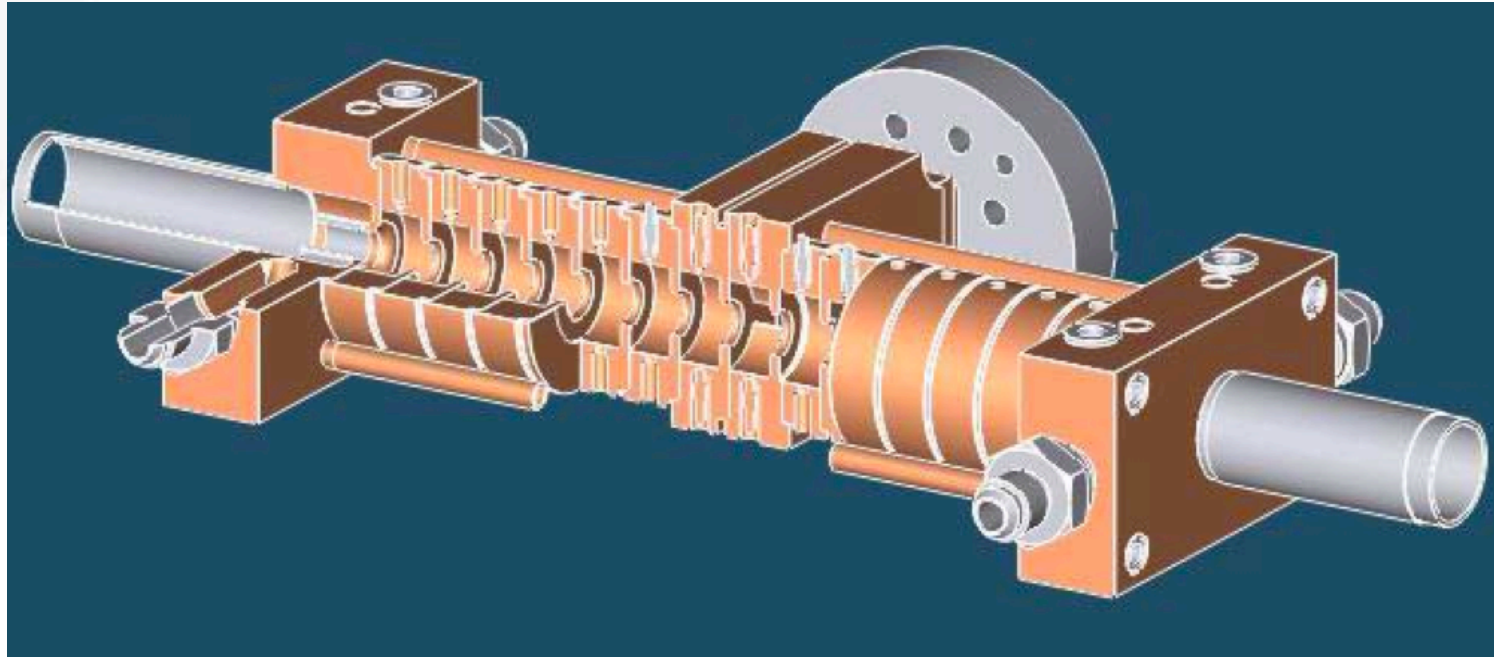


The goals of modeling?

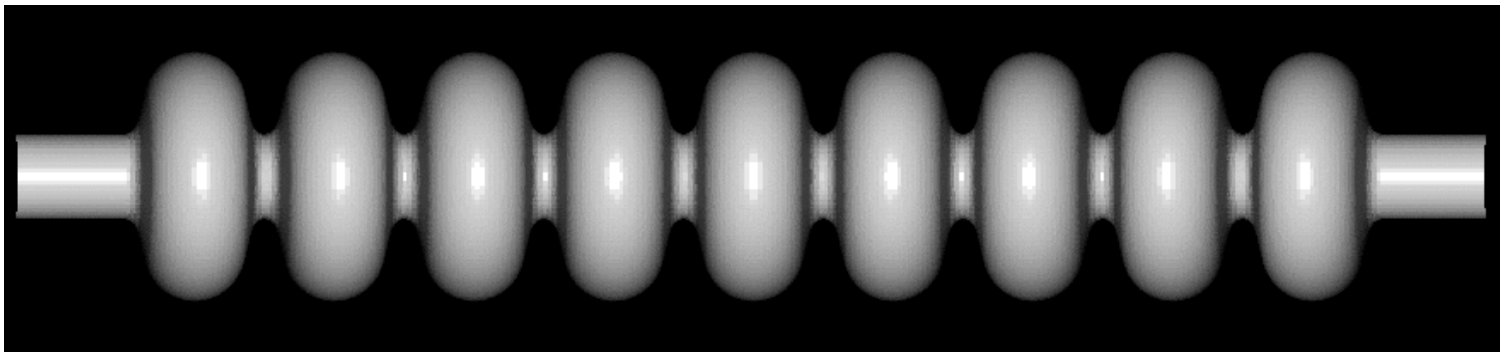
- Part of the design process
 - Create
 - Simulate
 - Build
 - Test
- Simulation for prediction of
 - Cavity losses
 - Instability
- In general for
 - Exploration
 - Confirmation
 - Elucidation



**Modeling allows one to answer questions
without construction cost**



NLC



ILC (Tesla)



Basic problem in charge particles moving in EM fields

- Maxwell

$$\frac{\partial \mathbf{B}}{\partial t} = -\nabla \times \mathbf{E}$$

$$\frac{\partial \mathbf{E}}{\partial t} = c^2 [\nabla \times \mathbf{B} - \mu_0 \mathbf{j}]$$

- Particle sources

$$\mathbf{j} = \sum q_i \mathbf{v}_i \delta(\mathbf{x} - \mathbf{x}_i)$$

- Particle dynamics

$$\frac{d(\gamma \mathbf{v})}{dt} = \frac{q_i}{m_i} [\mathbf{E}(\mathbf{x}_i, t) + \mathbf{v}_i \times \mathbf{B}(\mathbf{x}_i, t)]$$

$$\frac{d\mathbf{x}_i}{dt} = \mathbf{v}_i$$

Auxiliary equations

$$\nabla \cdot \mathbf{B} = 0$$

$$\nabla \cdot \mathbf{E} = \rho / \epsilon_0$$

$$\rho = \sum q_i \delta(\mathbf{x} - \mathbf{x}_i)$$



With much other physics added for a complete model

- Particle injection
- Dark currents
- Multipactoring
- Photon (short wavelength) production
- Surface resistance
- Secondary emission



ELECTROMAGNETICS



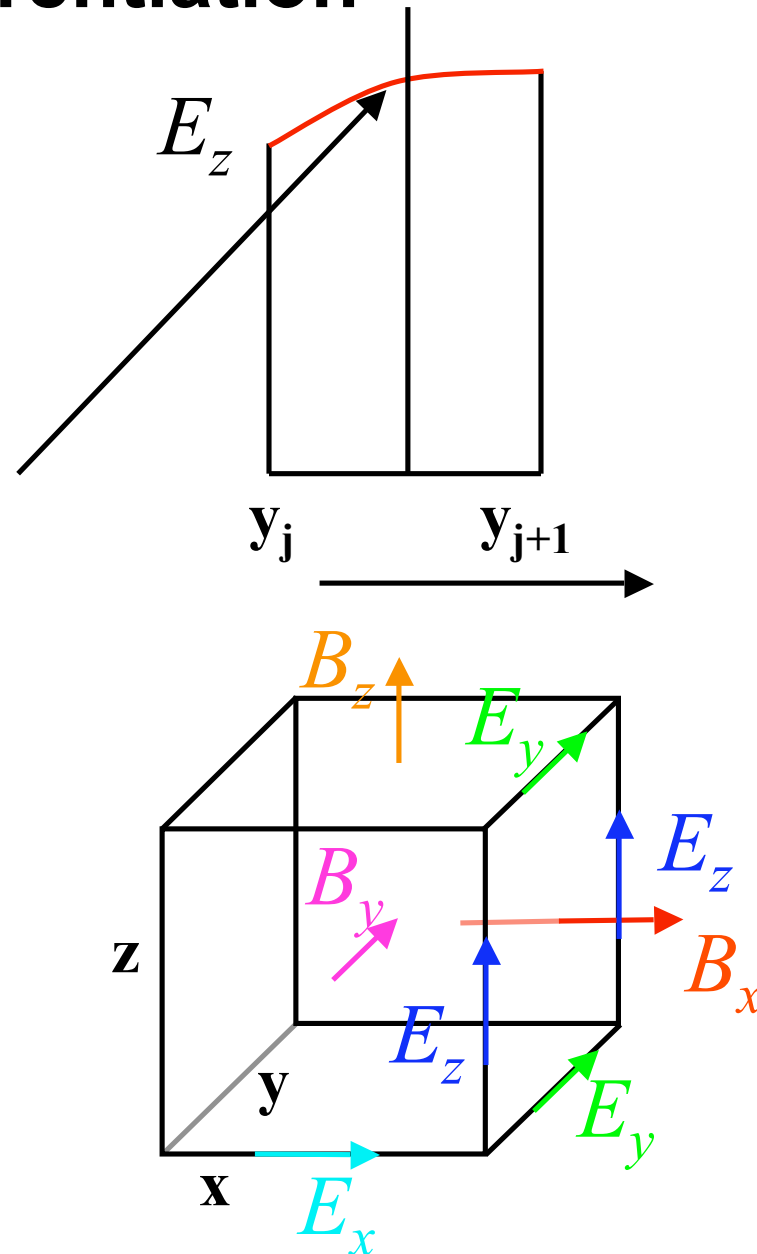
Yee: 2nd order accurate spatial differentiation

$$\frac{\partial B_x}{\partial t} = -\frac{\partial E_z}{\partial y} + \frac{\partial E_y}{\partial z}$$

- At the midpoint

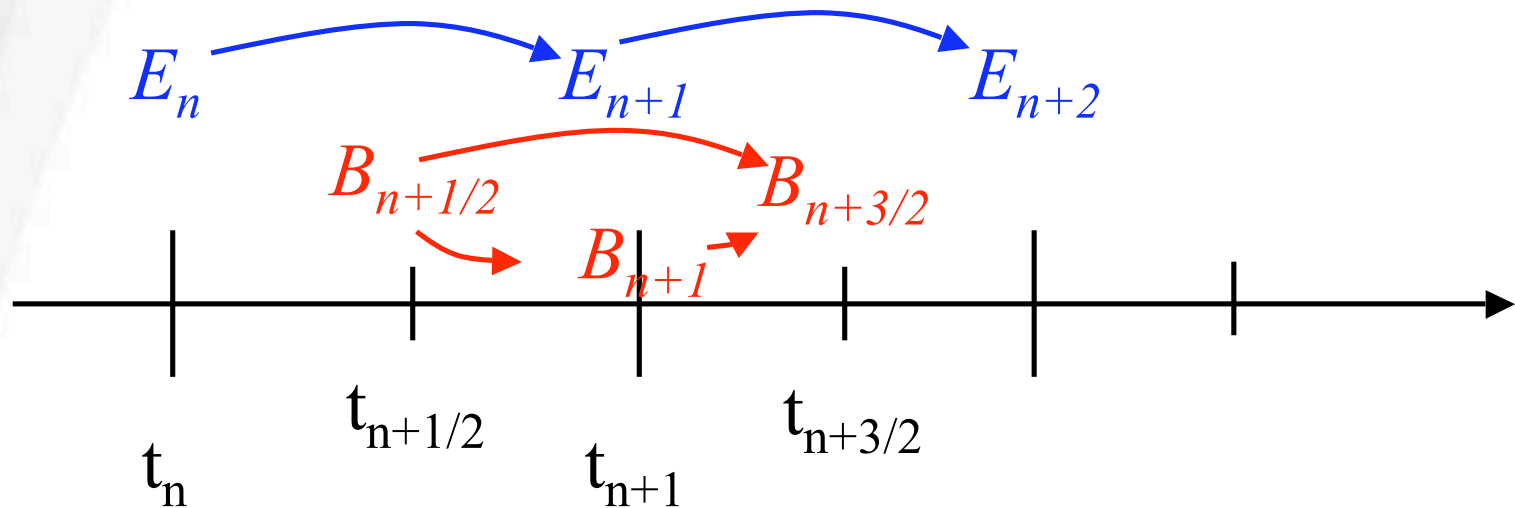
$$\frac{\partial E_z}{\partial y} = \frac{E_{z,j+1} - E_{z,j}}{\Delta y} + O(\Delta y^2)$$

- Leads to special layout of values in a cell
- *Yee mesh* gives 2nd order accuracy of spatial derivatives





Second-order in time by leap frog



$$\frac{\partial B_x}{\partial t} = -\frac{\partial E_z}{\partial y} + \frac{\partial E_y}{\partial z}$$

$$B_{x,i,j,k}^{n+1/2} - B_{x,i,j,k}^{n-1/2} = \Delta t \left(\frac{E_{z,i,j,k}^n - E_{z,i,j+1,k}^n}{\Delta y} + \frac{E_{y,i,j,k+1}^n - E_{y,i,j,k}^n}{\Delta z} \right)$$

- Time centered differences give second order accuracy in Δt
- Can get time-collocated values by half-stepping in B
- Similar for E update, except c^2 factor



Matrix representation useful for stability

$$\frac{dB_{x,i,j,k}}{dt} = \left(\frac{E_{z,i,j,k} - E_{z,i,j+1,k}}{\Delta y} + \frac{E_{y,i,j,k+1} - E_{y,i,j,k}}{\Delta z} \right)$$

$$\frac{d\mathbf{b}}{dt} = -\mathbf{C} \cdot \mathbf{e} \quad \frac{d\mathbf{e}}{dt} = c^2 \mathbf{C}' \cdot \mathbf{b} \quad \frac{d^2 \mathbf{b}}{dt^2} = -c^2 \mathbf{C} \cdot \mathbf{C}' \cdot \mathbf{b} = -\mathbf{D} \cdot \mathbf{b}$$

- Magnetic and electric spaces are different
- $\mathbf{C}$, $\mathbf{C}'$ are adjoints, so $\mathbf{D}$ is self-adjoint (symmetric)
- Diagonalize into separate harmonic oscillators
- Leap frog for harmonic oscillator, stability limit at

$$\omega_{\max} \Delta t_{CFL} = 2 \quad \Delta t_{CFL} = \frac{1}{c \sqrt{\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} + \frac{1}{\Delta z^2}}}$$



Gershgorin Circle Theorem gives stability bound

- Frequencies are eigenmodes of $D = c^2 C' C$
- Eigenvalues in range

$$0 < \omega^2 < \max \left(\sum_j |D_{ij}| \right) \text{ over } i$$

- Gives precise range for infinite grid
- Points to relation between coefficients and frequencies for other cases



Many other methods available

- Finite element - later
- Hamiltonian splitting (de Raedt): into exactly solvable parts
$$\frac{d(\mathbf{b}, \mathbf{e})}{dt} = \mathbf{A} \bullet (\mathbf{b}, \mathbf{e}) = \mathbf{M} \bullet \mathbf{N} \bullet (\mathbf{b}, \mathbf{e})$$
 - known: $\frac{d\mathbf{U}_M}{dt} = \mathbf{M} \bullet \mathbf{U}_M$ $\frac{d\mathbf{U}_N}{dt} = \mathbf{N} \bullet \mathbf{U}_N$
 - stable approximate solution (since unitary):
$$\mathbf{U}(\Delta t) = \mathbf{U}_N(\Delta t / 2) \bullet \mathbf{U}_M(\Delta t) \bullet \mathbf{U}_N(\Delta t / 2)$$
 - Similar to drift-kick of symplectic integration
 - Lee and Fornberg (2005) have improved method based on Zheng et al (1999)
- *Smith, Cary, Carlsson now have implicit, charge-conserving algorithm*



PARTICLES



Computing particle-particle interactions is prohibitive

- Coulomb interaction leads to N_p^2 force computations

$$\frac{d\gamma_i \mathbf{v}_i}{dt} = \frac{q_i}{\epsilon_0 m_i} \sum_j q_j \frac{\mathbf{x}_i - \mathbf{x}_j}{|\mathbf{x}_i - \mathbf{x}_j|^3}$$

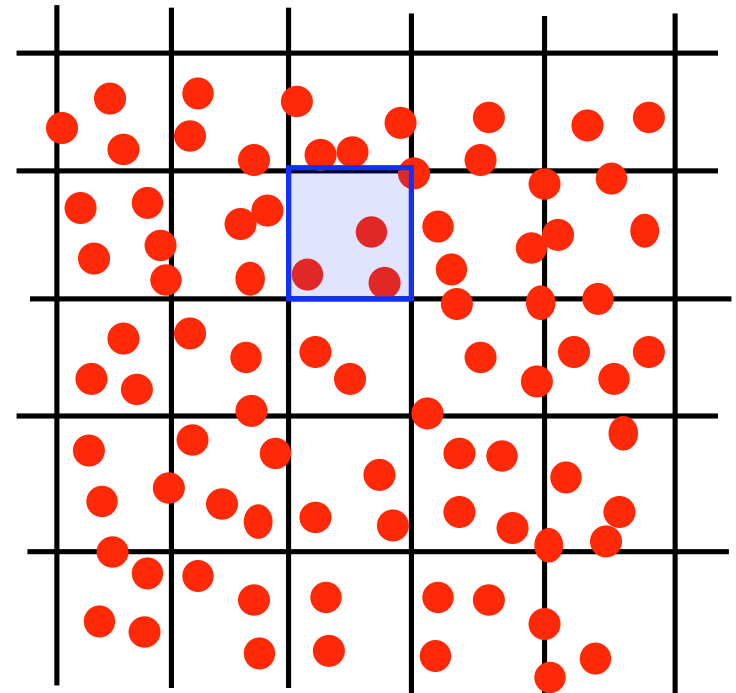
- Lenard-Weichert (retarded potentials) - worse due to need to keep history

$$\frac{d\gamma_i \mathbf{v}_i}{dt} = \frac{q_i}{\epsilon_0 m_i} \sum_j q_j \mathbf{F}_{ij}(\mathbf{x}_i, \mathbf{x}_j(t - \tau))$$



Particle In Cell (PIC) reduces to N_p scaling

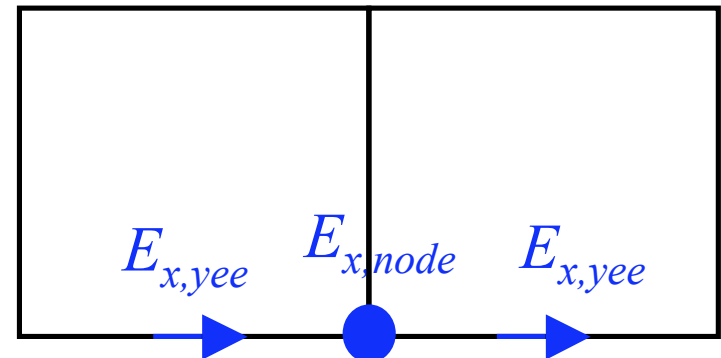
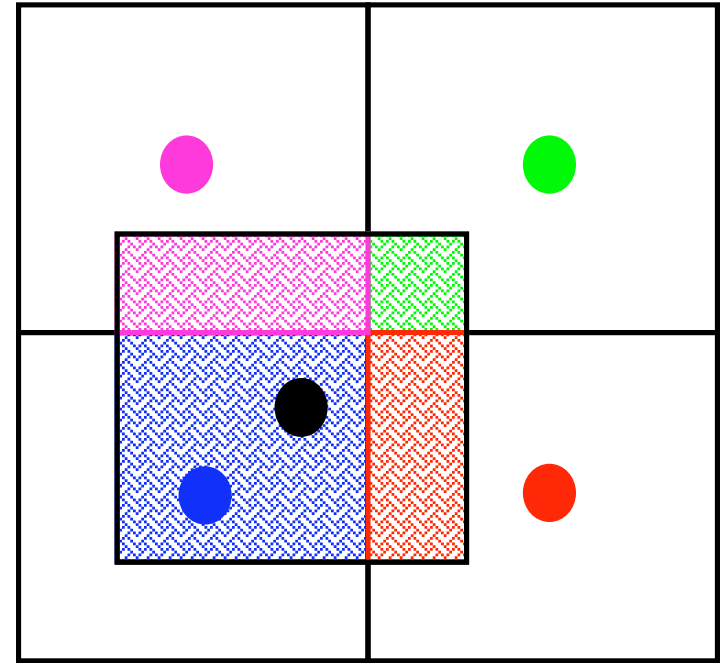
- Particle contributions to charges and currents are added to each cell: $O(N_p)$ operations
- Forces on a particle are found from interpolation of the cell values: $O(N_p)$ operations





Finding the force: interpolation (gather)

- Linear weighting for each dimension
 - 1D: linear
 - 2D: bilinear = area weighting
 - 3D: trilinear = volume weighting
- Force obtained through 1st order, error is 2nd order
- For simplicity, no loss of accuracy, weight first to nodal points





Efficiency

Avoiding Poisson



Only certain EM algorithms ensure Poisson satisfied

$\nabla \cdot \mathbf{E} = \rho / \epsilon_0$ satisfied
always if

$$\frac{\Delta E_x}{\Delta x} + \frac{\Delta E_y}{\Delta y} + \frac{\Delta E_z}{\Delta z} = \rho / \epsilon_0$$

$$\frac{\partial \mathbf{E}}{\partial t} = c^2 [\nabla \times \mathbf{B} - \mu_0 \mathbf{j}]$$

finite difference version

and
 $\nabla \cdot \mathbf{E} = \rho / \epsilon_0$ initially

$$\frac{\Delta E_x}{\Delta x} + \frac{\Delta E_y}{\Delta y} + \frac{\Delta E_z}{\Delta z} = \rho / \epsilon_0$$

and

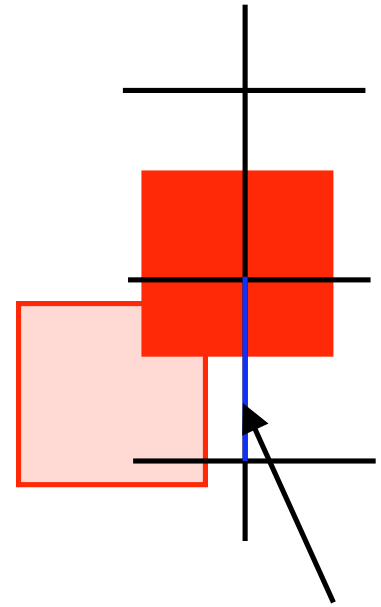
$$\frac{\partial \rho}{\partial t} = -\nabla \cdot \mathbf{j}$$

$$\frac{\Delta \rho}{\Delta t} = -\frac{\Delta j_x}{\Delta x} + \frac{\Delta j_y}{\Delta y} + \frac{\Delta j_z}{\Delta z}$$

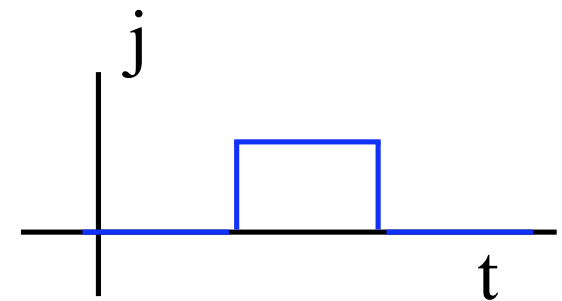


A special scatter ensures finite difference charge conservation

- Principle: apportion via some weighting
- Computing the charge density
 - Compute the current density and find the charge density from finite difference
 - Directly weight particles to the grid
- If these two methods do not agree, then one can have false charge buildup from the Ampere-Maxwell equation. Requires Poisson solve to remove.
- Villasenor/Buneman explicitly conserves charge, but is noisier



Current contrib. to this interface must match charge difference change across separated cells





EM algorithm must take *numerically* divergenceless to *numerically* divergenceless

$$\frac{\Delta E_x^n}{\Delta x} + \frac{\Delta E_y^n}{\Delta y} + \frac{\Delta E_z^n}{\Delta z} = 0$$

and

$$\mathbf{E}^{n+1} = \mathbf{M} \cdot \mathbf{E}^n$$

implies

$$\frac{\Delta E_x^{n+1}}{\Delta x} + \frac{\Delta E_y^{n+1}}{\Delta y} + \frac{\Delta E_z^{n+1}}{\Delta z} = 0$$

Mardahl and Verboncoeur show importance of getting this right

ELSEVIER

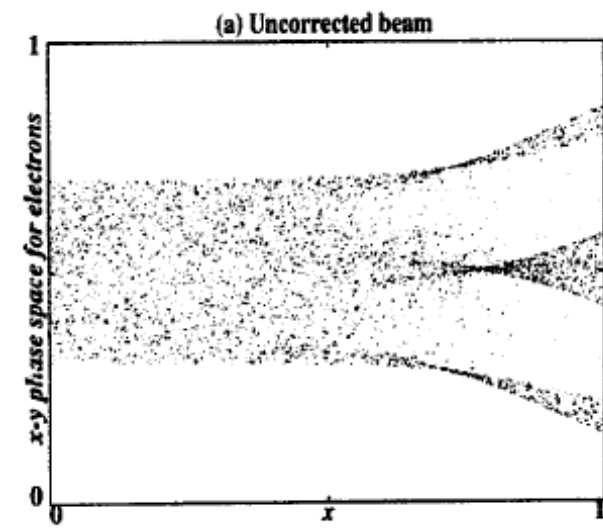
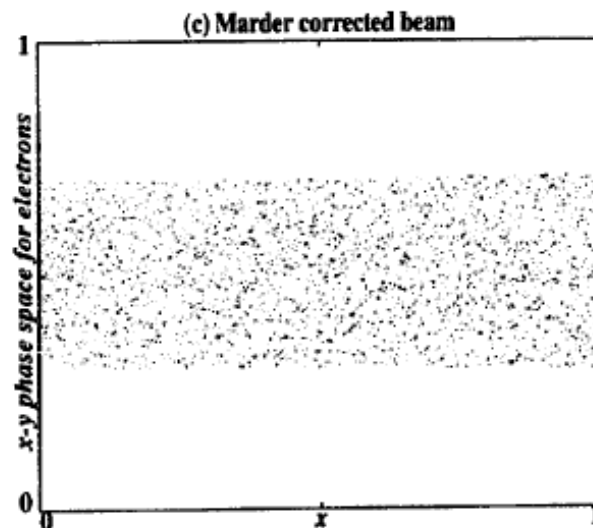
Computer Physics Communications 106 (1997) 219–229

Charge conservation in electromagnetic PIC codes; spectral comparison of Boris/DADI and Langdon–Marder methods

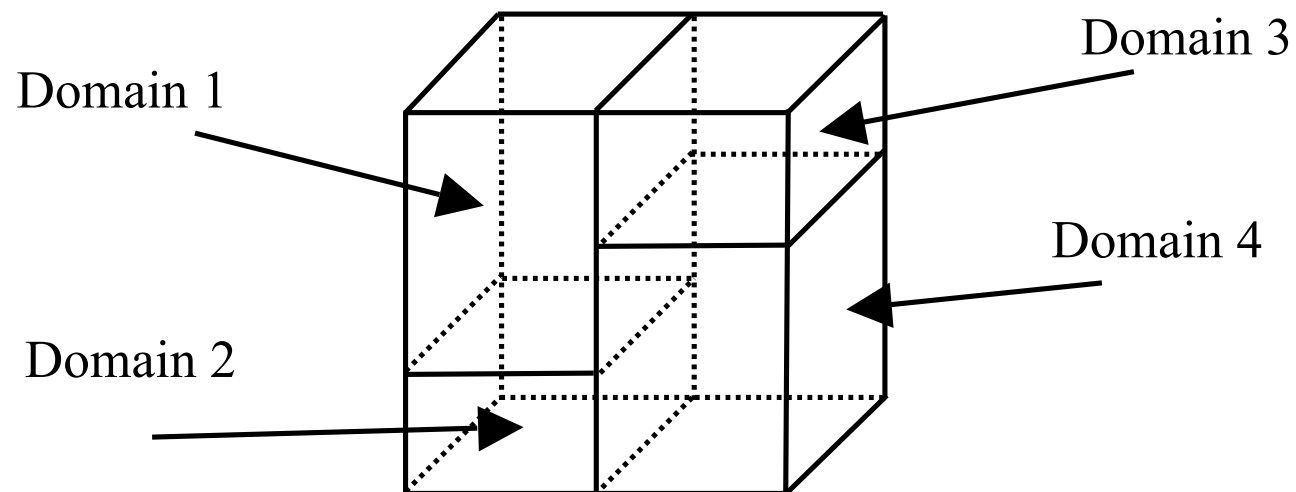
P.J. Mardahl¹, J.P. Verboncoeur

Cory Hall Box 173, Department of Electrical Engineering and Computer Science, University of California, Berkeley, CA 94720-1770, USA

Received 1 April 1997; revised 11 August 1997



Parallelism: domain decomposition





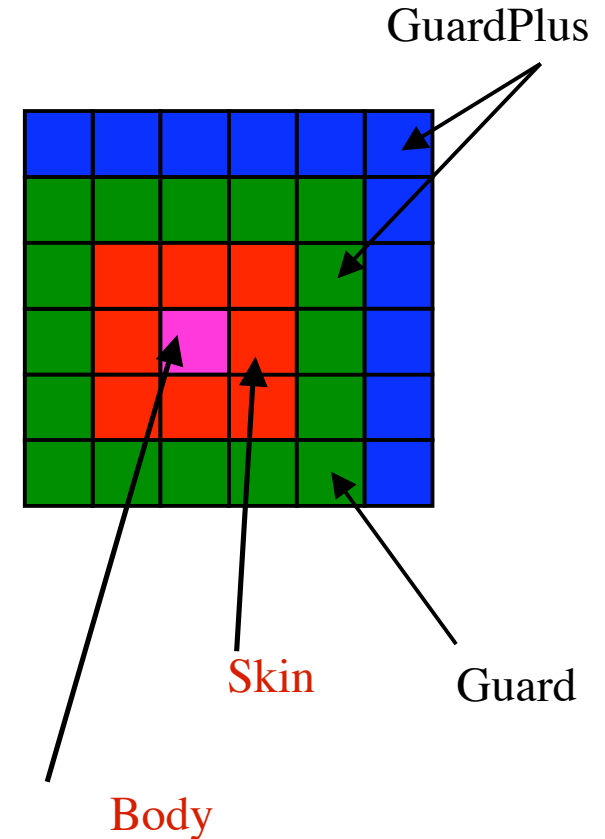
Parallelism rules of thumb

- Communication is expensive
- Global solves are really expensive



Overlap of communication and computation needed for speed

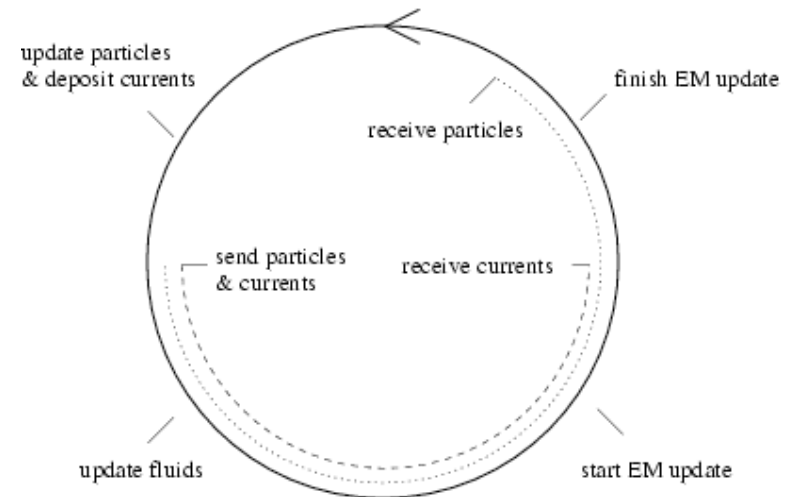
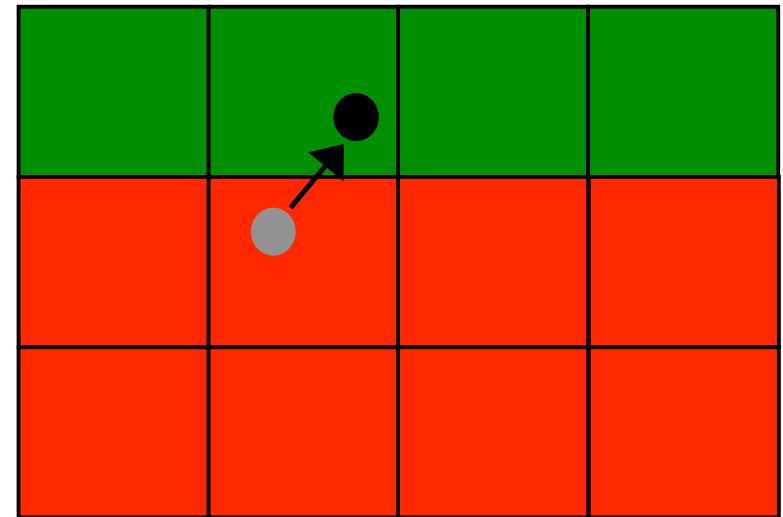
- Non overlap algorithms:
 - Compute domain
 - Send skin (outer edge)
 - Receive guard
 - Repeat
- Overlap algorithms
 - Compute skin
 - Send skin
 - Compute interior
 - Receive guard
 - Repeat





Similar overlap possible for particles

- Move particles and weight currents to grid
- Send currents needed by neighboring processors
- Send particles to neighboring processors
- Update B for half step
- Receive currents and add in
- Update E, B
- Receive particles



Without charge conserving current deposition, further costly global solve

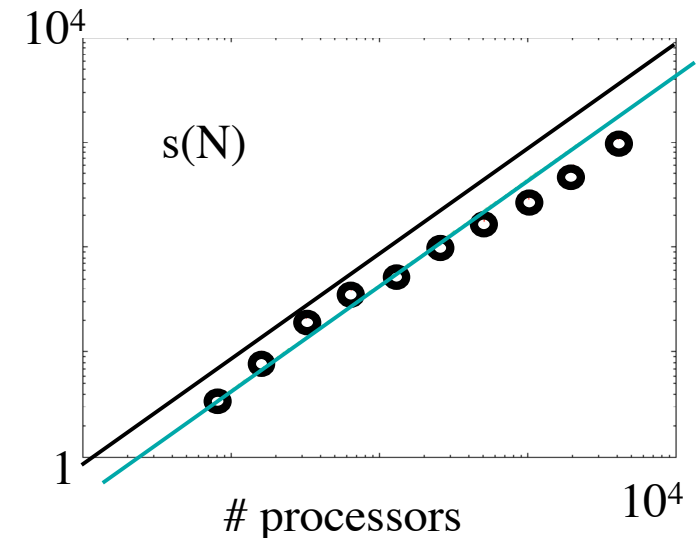


VORPAL implements basic algorithms in highly scalable manner

Object-oriented and flexible

(Arbitrary dimensional)

- Self-consistent EM modeling
 - Full EM or electrostatic + cavity mode
 - Particle in cell with relativistic or nonrelativistic dynamics
- But has other capabilities
 - Impact and field ionization
 - Fluid methods for plasma or neutral gases
 - Implicit EM
 - Secondary emission
- And is modern
 - Serial or Parallel (general domain decomposition)
 - Cross-platform (Linux, AIX, OS X, Windows)
 - Cross-platform binary data (HDF5)



**VORPAL scales well to
1,000's of processors
(strong scaling)**



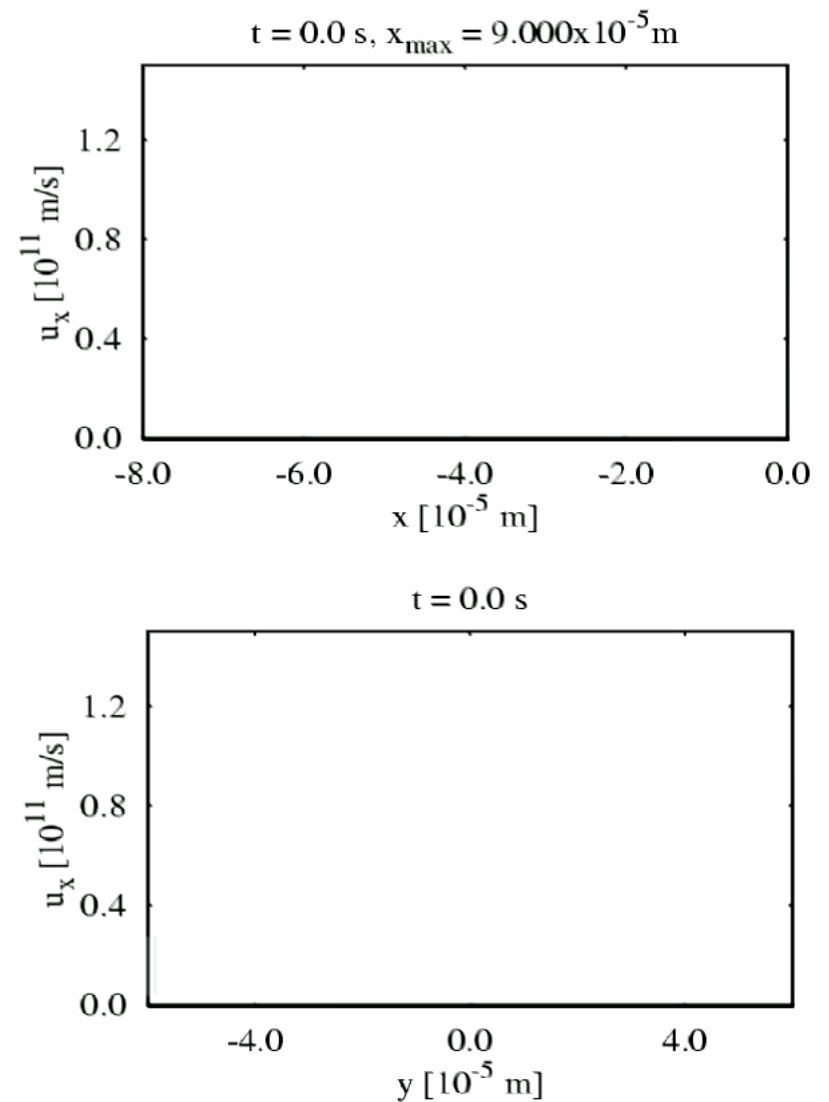
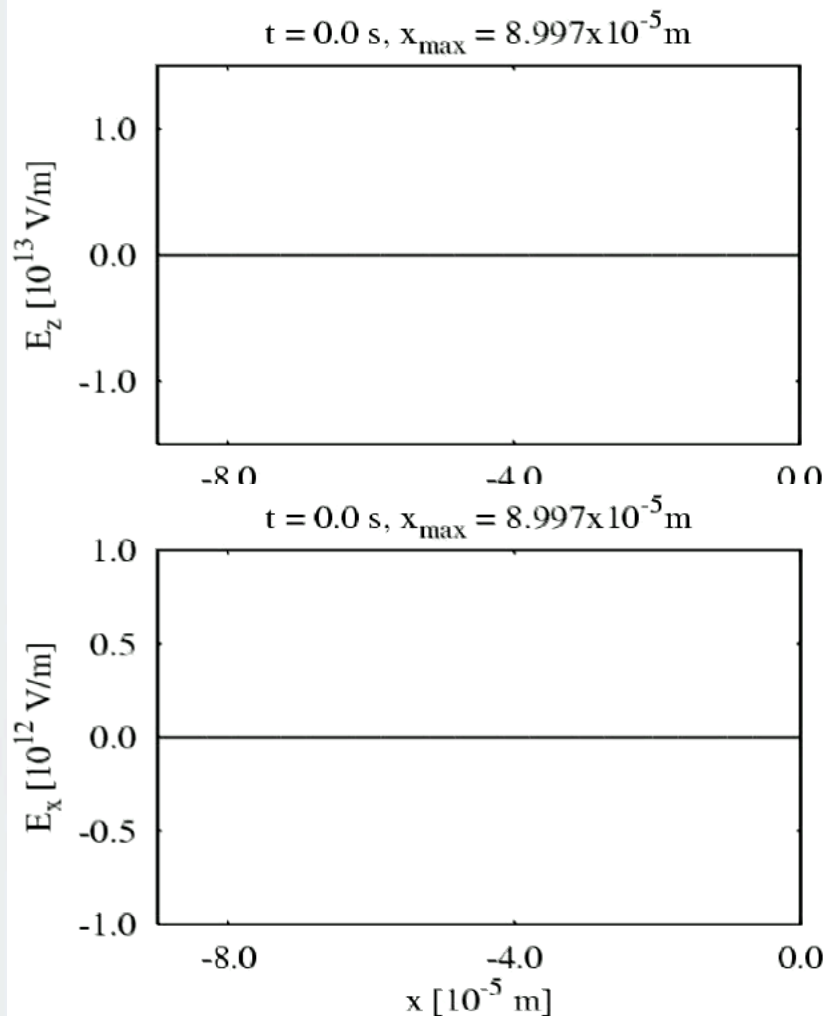
Simplest algorithm allows complex computations

- Example: formation of beams in laser-plasma interaction





Elucidation: long pulses shorten to resonance, capture, loading, acceleration





Simulations have found the hosing problem

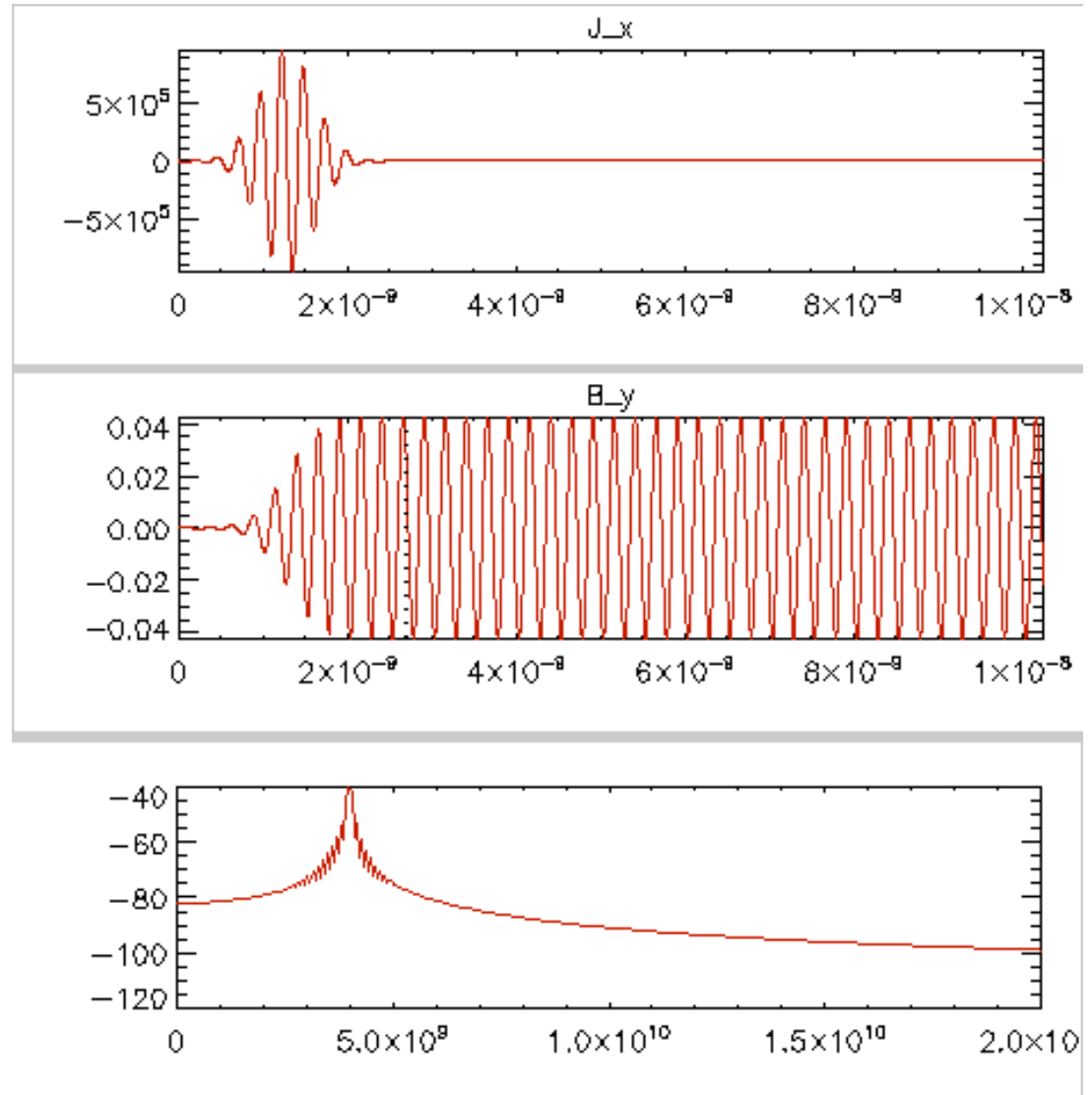


Complications: boundaries



Modes computed with combination of FFT and fitting

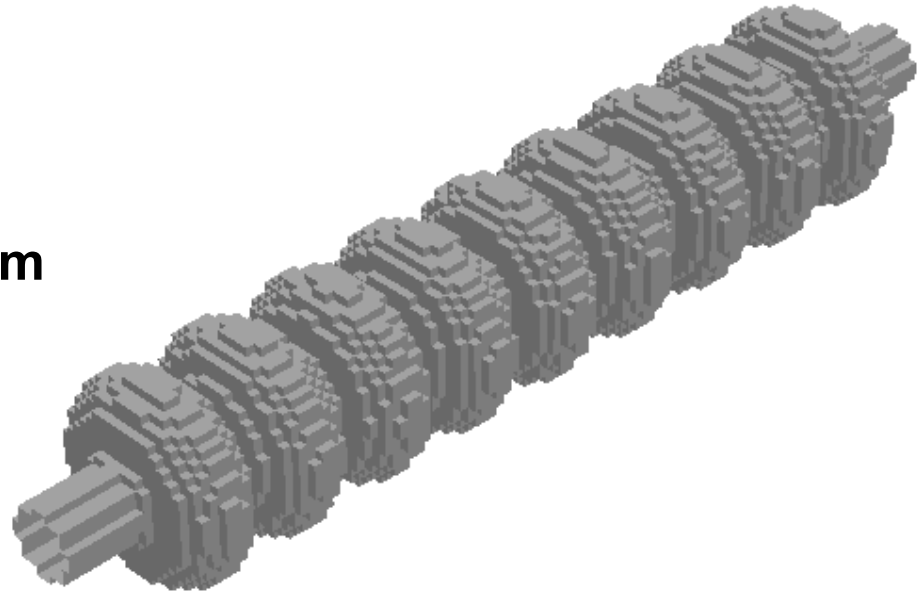
- Spherical cavity
- Resonant current driver
- FFT measurement of frequency, for accuracy by fitting





Early work on structured meshes had *stair-step* boundary conditions

**$120 \times 24 \times 24 = 71,424$ cells
= 215,000 degrees of freedom**

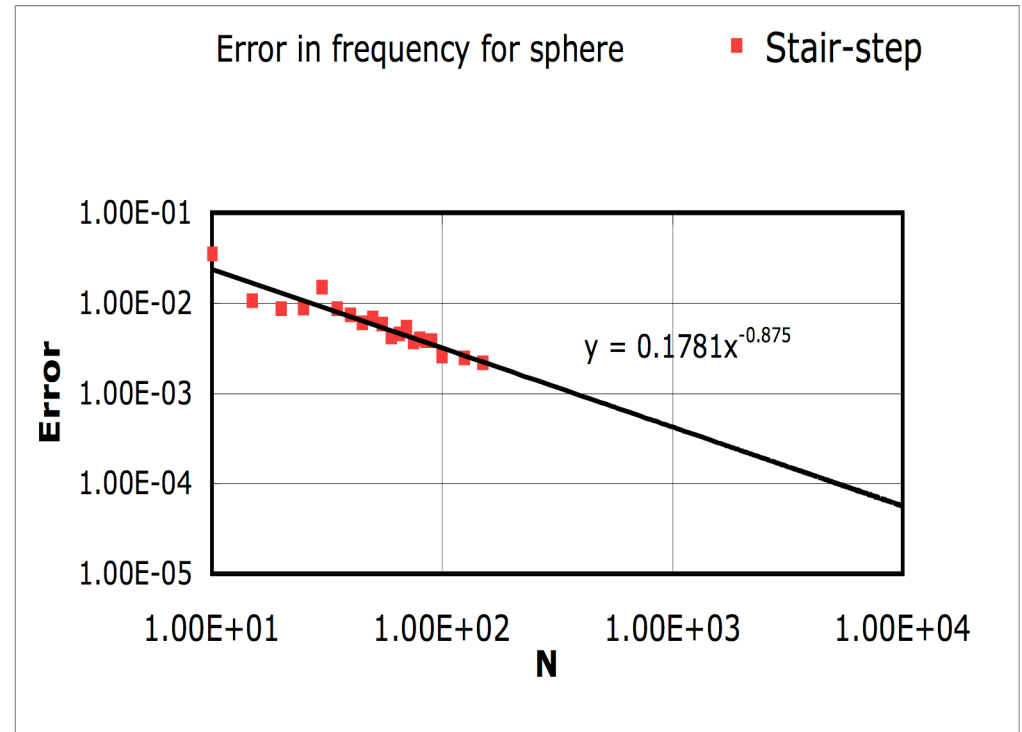


- $N (L/\Delta x)$ cells in each direction
- Error of $(\Delta x/L)^3$ at each surface cell
- $O(N^2)$ cells on surface
- Error = $N^2(\Delta x/L)^3 = O(1/N)$



Convergence studies confirm result, indicate modeling problem

- Stair-step error is 10^{-3} at 5000 cells per dimension, error linear with cell size
- 10^{11} cells for 3D problem



This approach will not give answer even on large, parallel hardware



Finite elements give one approach to improved boundary modeling

- Tau3P, HFSS, ...

$$\mathbf{B} = \sum b_k(t) \mathbf{u}_k^B(x) \quad \mathbf{E} = \sum e_\ell(t) \mathbf{u}_\ell^E(x)$$

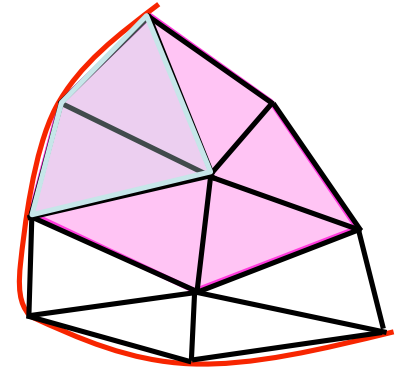
$$\frac{\partial \mathbf{B}}{\partial t} = \sum \frac{db_k}{dt}(t) \mathbf{u}_k^B(x) \quad \nabla \times \mathbf{E} = \sum e_\ell(t) \nabla \times \mathbf{u}_\ell^E(x)$$

$$\sum \frac{db_k}{dt}(t) \mathbf{u}_k^B(x) = - \sum e_\ell(t) \nabla \times \mathbf{u}_\ell^E(x)$$

$$\int d^3x \sum_k \frac{db_k}{dt}(t) \mathbf{u}_{k'}^B(\mathbf{x}) \mathbf{u}_k^B(\mathbf{x}) = - \int d^3x \sum_\ell e_\ell(t) \mathbf{u}_{k'}^B(\mathbf{x}) \cdot \nabla \times \mathbf{u}_\ell^E(\mathbf{x})$$

$$\mathbf{M}_b \cdot \frac{d\mathbf{b}}{dt} = -\mathbf{C} \cdot \mathbf{e}$$

$$\mathbf{M}_e \cdot \frac{d\mathbf{e}}{dt} = c^2 \mathbf{C}' \cdot \mathbf{b}$$





Finite elements require global solves, more intense particle calculations

- Global mass matrix inversion required at each step

$$\mathbf{M}_b \cdot \frac{d\mathbf{b}}{dt} = -\mathbf{C} \cdot \mathbf{e}$$

- Self consistency difficult and charge conservation not guaranteed

$$\mathbf{M}_e \cdot \frac{d\mathbf{e}}{dt} = c^2 (\mathbf{C}' \cdot \mathbf{b} - \mu_0 \mathbf{j})$$

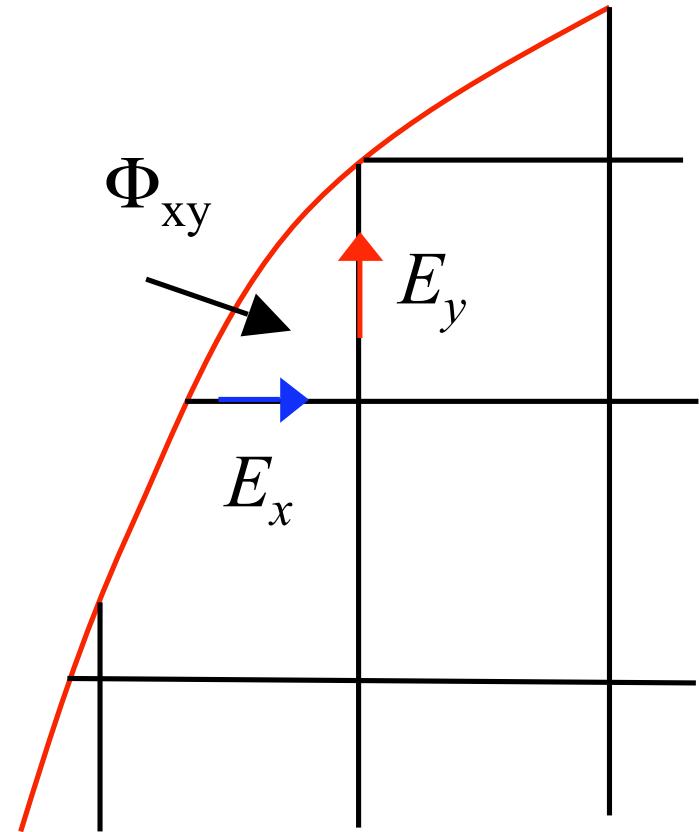
$$j_\ell = \sum_{ptcls\ i} q_i \mathbf{v}_i \mathbf{u}_\ell^E(\mathbf{x}_i((n+1/2)\Delta t))$$

- Difficult to follow particles
 - List of regions
 - List of FE's with support in that region
 - Complex FE element evaluation at each time step for each particle



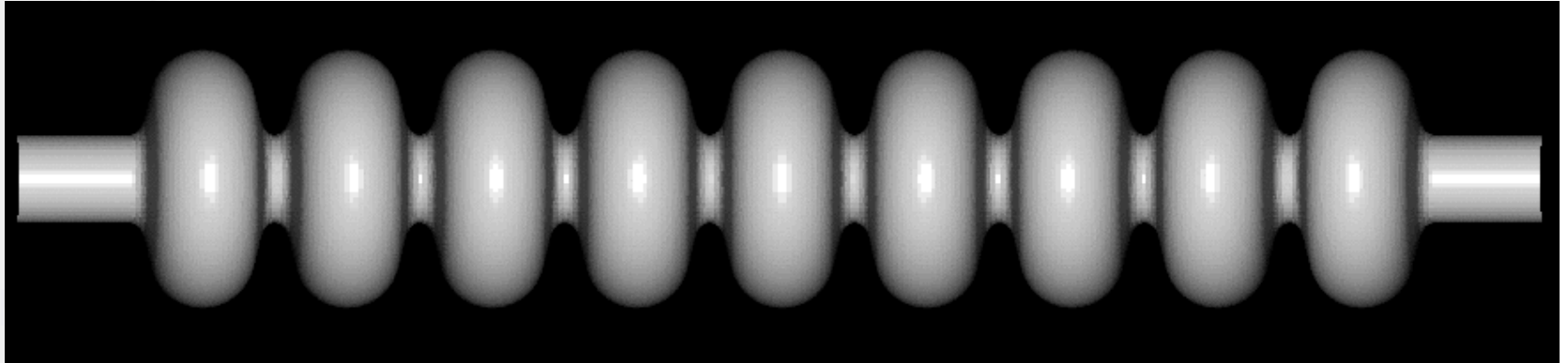
Resurgence of regular grids: cut cells give same accuracy as finite elements

- For cells fully interior, us regular update
- For boundary cells:
 - Store areas and lengths
 - Update fluxes via
$$\dot{\Phi}_{xy} = -E_x \ell_x - E_y \ell_y$$
 - Update fields via
$$B_z = \Phi_{xy} / A_{xy}$$

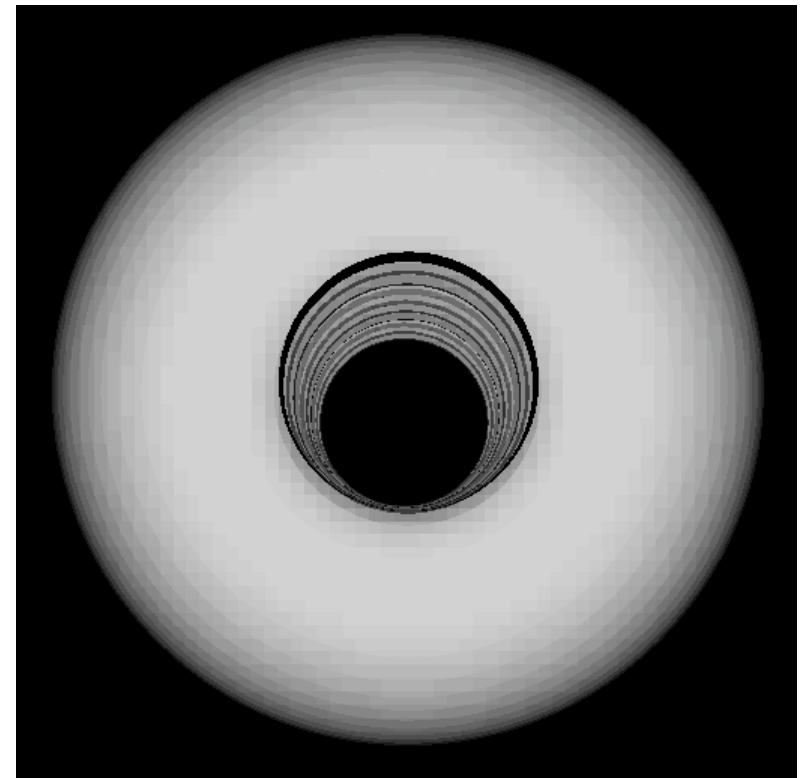




Cut-cell boundary conditions accurately represent geometry



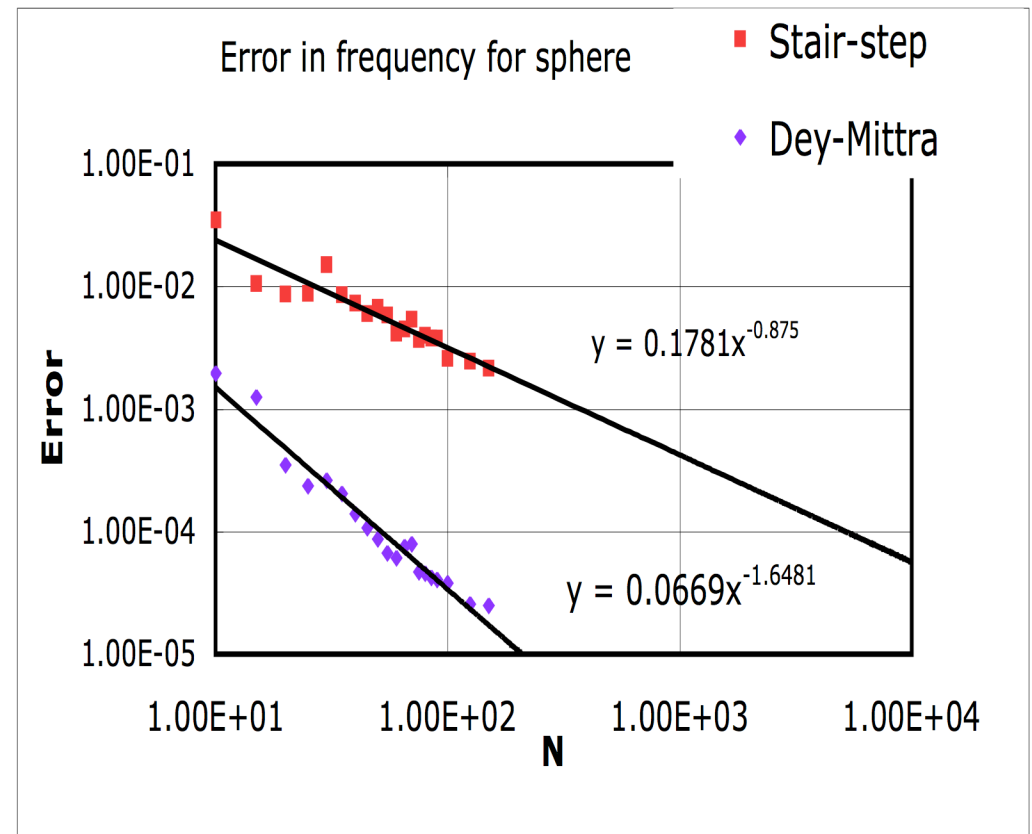
- Tesla 2000 cavities
- 312x56x56 (10^6) cells





Dey-Mittra (1997) cut-cells allow 10^{-4} accuracy

- Fewer than 10^7 cells for cavity modeling at one part in 10^5
- Implementation exists now in VORPAL
- No significant additional computational cost





Beam problems provide motivation for further work

- SRF accelerating cavities
- SRF guns
- Crab cavities



Regular, structured grids allow for self-consistent integration of particles

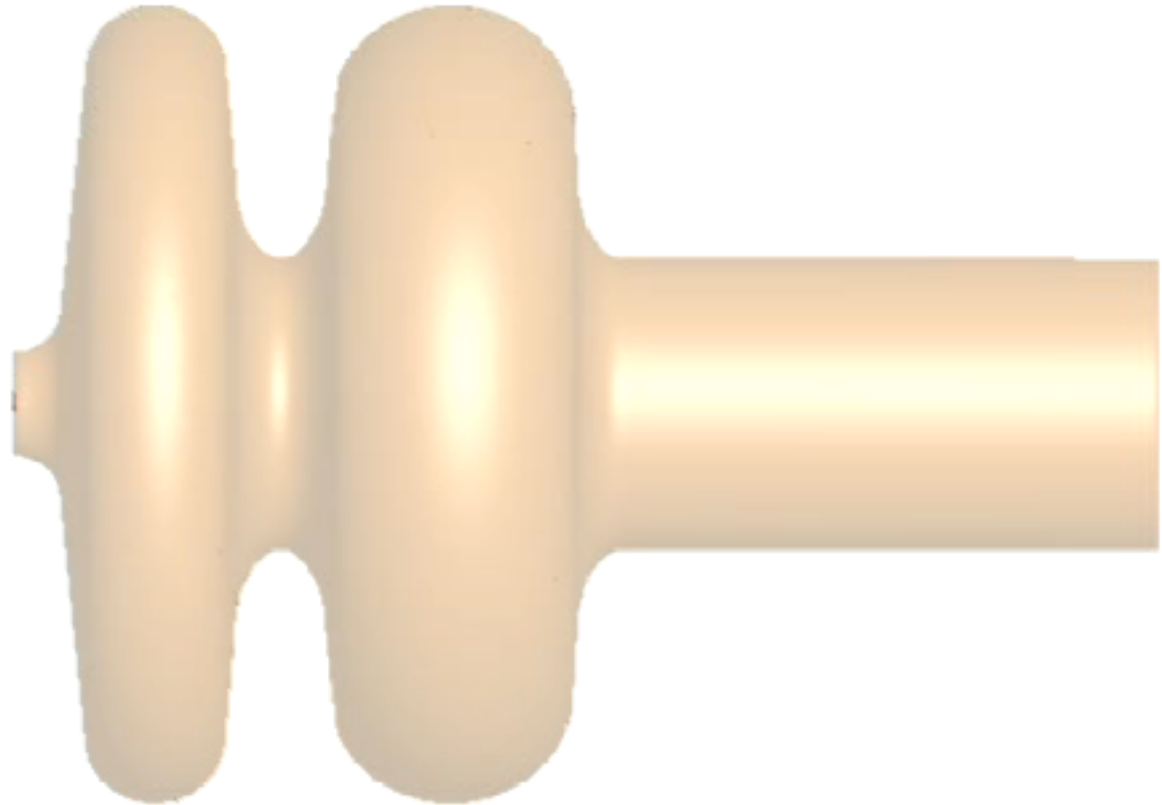


Wakefield for Tesla cavities computed by VORPAL in 3D



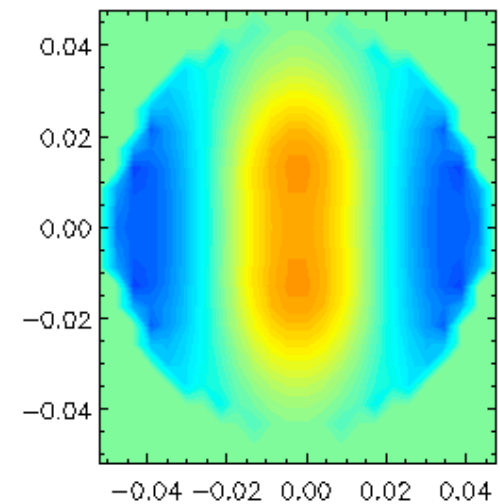
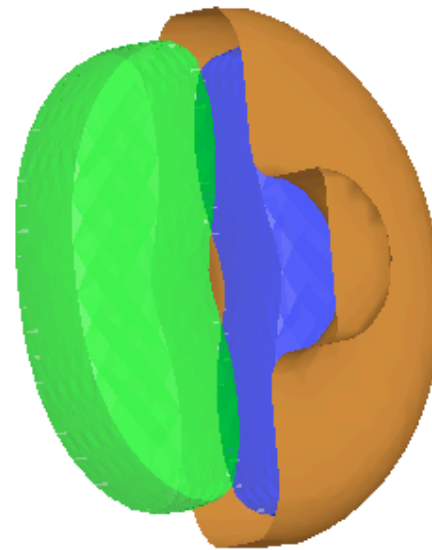
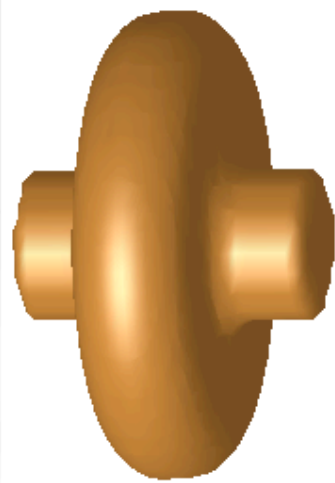
Self-consistent EM gun simulations in complex cavities

- Emitted beam
- Wakes from constrictions



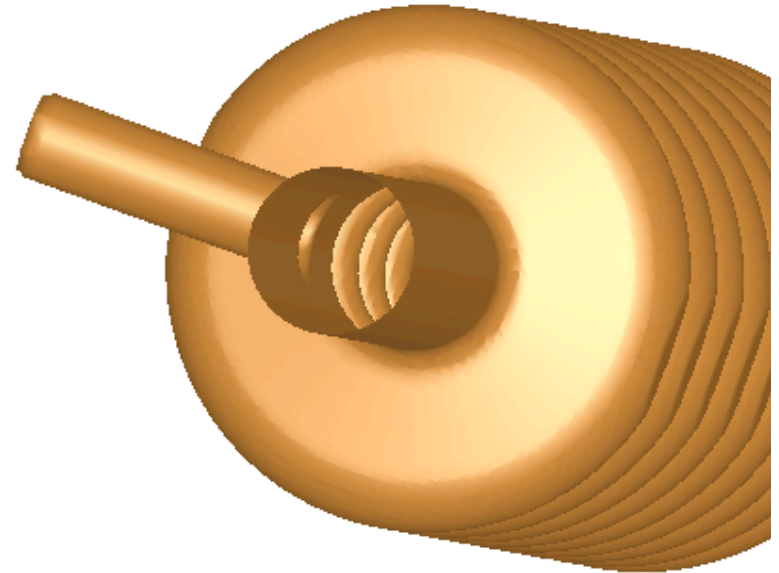
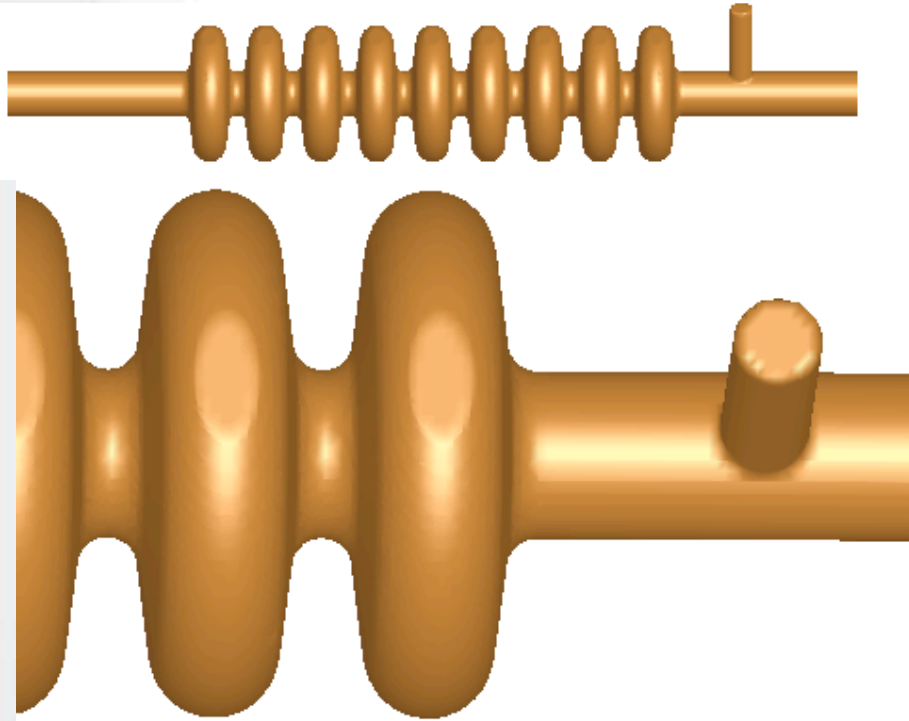


Now simulating dipole modes in symmetric cavities





Crab cavity generation, visualization, computation of splitting

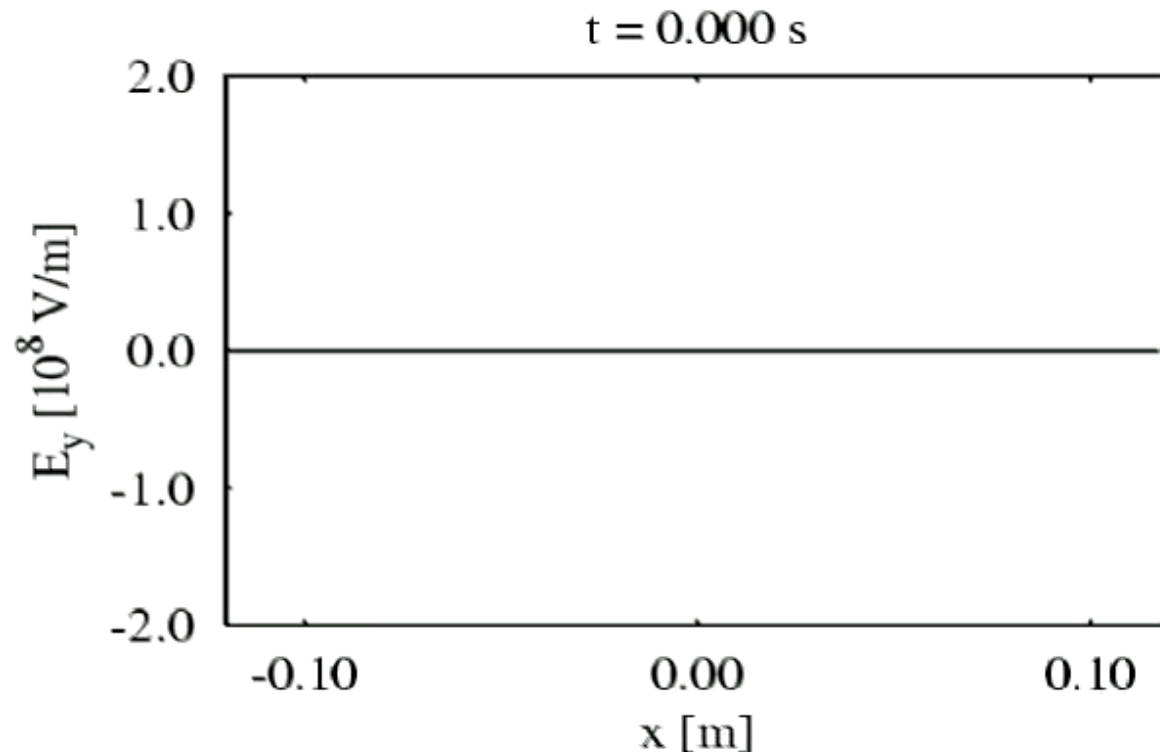


- CAD representations
- Python coding of shapes



Dey-Mittra problem: small triangles give high frequencies, small time steps

- B update matrix coefs $\sim$ length/area
- Length/area becomes infinite as area vanishes
- Get localized, high-frequency modes
- Must throw out small cell fragments

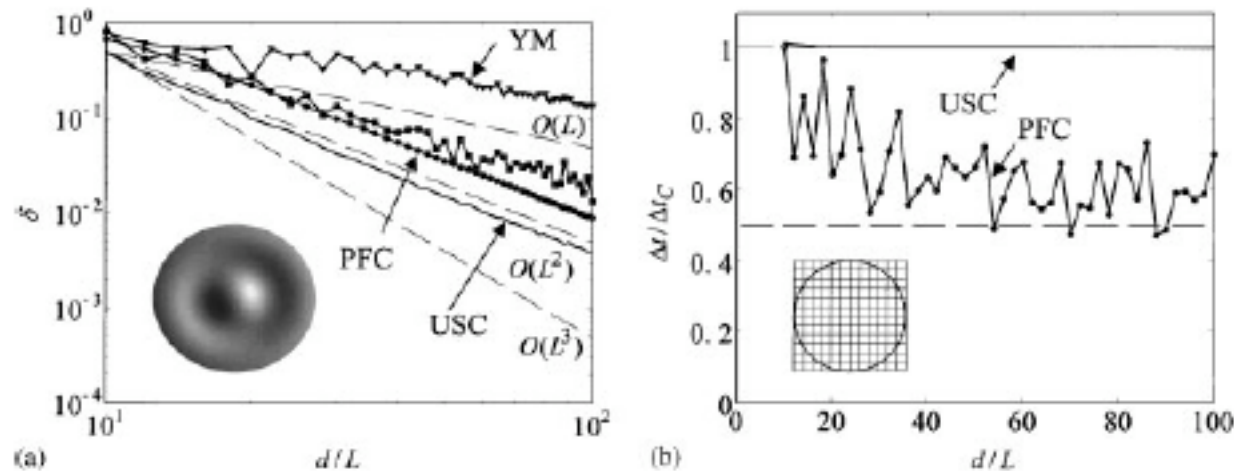


Improvement on cut-cell recently discovered

INTERNATIONAL JOURNAL OF NUMERICAL MODELLING: ELECTRONIC NETWORKS, DEVICES AND FIELDS
Int. J. Numer. Model. 2003; 16:127–141 (DOI: 10.1002/jnm.488)

A uniformly stable conformal FDTD-method in Cartesian grids

I. A. Zagorodnov^{*,†}, R. Schuhmann and T. Weiland



- New method gives error lower than Dey-Mittra
- Does not have reduction of stable Δt
- Favorable properties re particle introduction
- Now being implemented



Each new study inspires capability, brings requests

- Laser-plasma: self-consistency, parallelism
 - Higher-order particle shapes
- Accelerating cavities: shape modeling
 - Higher-order field to particle near walls
 - Resistive walls for complex shapes
 - Implicit EM solvers
- Electron guns
 - Better emission models
- Crab cavities
 - Notch filters, LOM couplers



Summary

- Self-consistent EM modeling has progressed
 - High-performance, self-consistent computations
 - Accurate treatment of boundaries
 - Secondary emission
 - Absolutely stable charge-conserving algorithm
- Remain algorithm needs
 - Conformal resistive walls
- Remain implementation needs
 - Surface resistance
 - Dark currents
 - Photonic emission
 - Absolutely stable charge-conserving algorithm
- Remains work in simulation setup
 - Defines cavity shapes
 - Define particle beams