

# Electromagnetism I

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Lecture 14

# Dielectric Energy



- Simple consideration of simple capacitor

$$W = \frac{1}{2} CV^2$$

- With dielectric inside

$$C = \epsilon_r C_{vacuum}$$

- Without dielectric

$$W = \frac{\epsilon_0}{2} \int \mathbf{E}^2 dV$$

- Suggests with dielectric

$$W = \frac{1}{2} \int \mathbf{D} \cdot \mathbf{E} dV$$

# Atomic model again

- Assume the “atomic springs” have constant  $k$

$$E_{spring} = \frac{1}{2} k (x_+ - x_-)^2 = \frac{1}{2} k \frac{q^2 E^2}{k^2}$$

- In terms of individual atomic dipole moments

$$p = q(x_+ - x_-) = \frac{q^2 E}{k}$$

- When  $n$  is the number of dipole moments per volume, the energy/volume in the springs is

$$\frac{U_{spring}}{Volume} = \frac{1}{2} (np) E = \frac{1}{2} P \times E$$

- The total energy in the springs generalizes to

$$U_{spring} = \frac{1}{2} \int \mathbf{P} \cdot \mathbf{E} dV$$

# Total Energy



- Electromagnetic field energy plus spring energy for a linear dielectric is

$$W = U_{em} + U_{spring} = \frac{\epsilon_0}{2} \int \mathbf{E} \cdot \mathbf{E} dV + \frac{1}{2} \int \epsilon_0 \chi_e \mathbf{E} \cdot \mathbf{E} dV = \frac{1}{2} \int \mathbf{D} \cdot \mathbf{E} dV$$

- Griffiths “add free charge” derivation. Start with 2.43 version of the work

$$W = \frac{1}{2} \int \rho \phi dV$$

where the potential  $\phi$  is the total potential including any material polarization effects. Generally, for a given free charge distribution the total potential is proportional (but will have a different space distribution  $\phi = \alpha(\mathbf{r})\rho_f$ ). Adding free charge  $\Delta\rho_f$

$$\Delta W = \frac{1}{2} \int \alpha (\rho_f + \Delta \rho_f)^2 dV = \int (\Delta \rho_f) \phi dV = \int \nabla \cdot (\Delta \mathbf{D}) \phi dV$$

- “Integrating by parts”

$$\nabla \cdot (\phi \Delta \mathbf{D}) = \nabla \phi \cdot \Delta \mathbf{D} + \phi \nabla \cdot (\Delta \mathbf{D})$$

$$\Delta W = \int [-\nabla \phi \cdot \Delta \mathbf{D} + \nabla \cdot (\phi \Delta \mathbf{D})] dV$$

$$= \int \mathbf{E} \cdot \Delta \mathbf{D} dV + \int \phi \Delta \mathbf{D} \cdot \hat{n} da$$

Boundary integral vanishes at large radii

- For linear dielectric

$$\frac{1}{2} \Delta (\mathbf{D} \cdot \mathbf{E}) = \frac{1}{2} \Delta (\epsilon \mathbf{E} \cdot \mathbf{E}) = \epsilon \Delta \mathbf{E} \cdot \mathbf{E} = \Delta \mathbf{D} \cdot \mathbf{E}$$

$$W = \frac{1}{2} \int \mathbf{D} \cdot \mathbf{E} dV$$

# Magnetic Fields



- Static magnetic fields (magnetostatics) produced by
  - Aligned atomic electron currents (permanent magnets)
  - Steady currents in wires (electromagnets)
- Unfortunate terminology problem
  - $\mathbf{B}$  is uniformly the notation for a (pseudo)vector field called by Griffiths the “magnetic field” and by other authors the “magnetic induction field”. In this latter case,  $\mathbf{H}$ , which will be defined in Chapter 6, is called the “magnetic field”. MKSA Units

$$[\mathbf{B}] = \text{Tesla (T)} = \frac{\text{Weber}}{\text{m}^2} = \frac{\text{V sec}}{\text{m}^2} = \frac{\text{Nt}}{\text{A m}}$$

$$[\mathbf{H}] = \frac{\text{A}}{\text{m}}$$

# Lorentz Force



- Total electromagnetic force on a charged particle

$$\mathbf{F} = q(\mathbf{E} + \mathbf{v} \times \mathbf{B})$$

- Force perpendicular to both velocity and magnetic field direction
- Magnetic fields can do no work on charged particles

$$\Delta T = \int \mathbf{F} \cdot d\mathbf{l}$$

$$\dot{T} = \mathbf{F} \cdot \mathbf{v}$$

- For magnetic forces

$$\dot{T} = q(\mathbf{v} \times \mathbf{B}) \cdot \mathbf{v} = 0$$

# Charged Particle Motion



- For a uniform magnetic field (say in z-direction)

$$\mathbf{F}_B = m\dot{\mathbf{v}} = q\mathbf{v} \times \mathbf{B} = q \begin{vmatrix} \hat{x} & \hat{y} & \hat{z} \\ v_x & v_y & v_z \\ 0 & 0 & B_z \end{vmatrix} = qB_z v_y \hat{x} - qB_z v_x \hat{y}$$

- Equations of motion

$$\dot{v}_x = \frac{qB_z}{m} v_y$$

$$\dot{v}_y = -\frac{qB_z}{m} v_x$$

$$\dot{v}_z = 0$$



# Circles!

- Simple harmonic motion in each degree of freedom

$$\frac{d}{dt}(v_x^2 + v_y^2) = 2 \frac{qB_z}{m} (v_x v_y - v_y v_x) = 0$$

$$\ddot{v}_x = \frac{qB_z}{m} \dot{v}_y = -\left(\frac{qB_z}{m}\right)^2 v_x$$

$$\ddot{v}_y = -\frac{qB_z}{m} \dot{v}_x = -\left(\frac{qB_z}{m}\right)^2 v_y$$

$$\dot{v}_z = 0$$

- Cyclotron (angular) frequency

$$\omega_c = \frac{qB_z}{m} \quad [\omega_c] = \frac{\text{C V sec}}{\text{kg m}^2} = \frac{1}{\text{sec}}$$

- Radius of orbit

$$\omega_c R = \sqrt{v_x^2 + v_y^2}$$